

L* Number	Hits	Search Text	DB	Time stamp
1	70	(pet near3 robot) and sony	USPAT; US-PGPUB	2004/01/23 07:49
2	43	(pet near3 robot) and sony and (voice speech)	USPAT; US-PGPUB	2004/01/23 07:49
-	0	704/272.ccls. and (behavior with speech) and (behavior with (touch pressure)) and prosody	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/01/20 10:55
-	0	704/\$.ccls. and (behavior with speech) and (behavior with (touch pressure)) and prosody	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/01/20 10:55
-	0	(behavior with speech) and (behavior with (touch pressure)) and prosody	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/01/20 10:55
-	0	(behavior with speech) and (behavior with (touch pressure)) and prosody	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/01/20 10:56
-	0	behavior and(touch pressure) and prosody and 704/272.ccls.	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/01/20 10:56
-	19	behavior and(touch pressure) and prosody and 704/\$	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/01/20 11:01
-	0	behavior and(touch pressure) and prosody and 446/\$.ccls.	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/01/20 11:02
-	0	response and(touch pressure) and prosody and 704/272.ccls.	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/01/20 11:02
-	214	response and(touch pressure) and prosody and 704/275.ccls. 704/272.ccls.	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/01/20 11:02
-	11	response and(touch pressure) and prosody and 704/275.ccls. 704/272.ccls. and robot	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/01/20 11:04
-	0	response and(touch pressure) and prosody and 704/275.ccls. and 704/272.ccls. and robot	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/01/20 11:05
-	2	response and(touch pressure) and prosody and (704/275.ccls. 704/272.ccls.) and robot	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/01/20 11:05
-	9	response and(touch pressure) and prosody and (704/\$.ccls.) and robot	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/01/20 11:19
-	14	response and(touch pressure) and prosody and robot	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/01/20 11:10
-	14	(behavior response action) and(touch pressure) and prosody and robot	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/01/20 11:10
-	21	(behavior response action) and(touch pressure) and prosody and (toy robot "novelty item")	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/01/20 13:03

-;	2	6160986.pn.	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/01/20 11:12
-	21	(touch pressure) and prosody and (toy robot "novelty item")	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/01/20 11:19
-	44	prosody and (toy robot "novelty item")	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/01/20 11:14
-	261	(touch pressure) and emotion and (toy robot "novelty item")	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/01/20 11:19
-	17	response and(touch pressure) and emotion and (704/\$.ccls.) and robot	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/01/20 11:22
-	56	response and(touch pressure) and emotion and (toy robot) and dictionary	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/01/20 11:24
-	210	response and(touch pressure) and emotion and (toy robot)	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/01/20 14:39
-	67	response and(touch pressure) and emotion and (pet near3 robot)	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/01/20 11:41
-	79	"pet robot" and emotion	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/01/20 11:46
-	31	"pet robot" and emotion and (recogn\$6 near4 (speech voice))	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/01/20 12:14
-	130	"robot" and (prosody prosodic emotion) and (recogn\$6 near4 (speech voice))	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/01/20 12:28
-	30	(toy robot pet "novelty item") and (detect\$4 near4 (prosody prosodic emotion)) and (recogn\$6 near4 (speech voice))	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/01/20 12:57
-	10	interactive near3 pet near3 robot	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/01/20 12:58
-	11	("4657104" "5465525" "5903988" "5963712" "6038493" "6058385" "6134580" "6234902" "6275773" "6282460" "6321140").PN.	USPAT	2004/01/20 12:59
-	63	(behavior response action) and(touch pressure) and prosody	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/01/20 13:02
-	21	(behavior response action) and(touch pressure) and prosody and (pet toy robot "novelty item")	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/01/20 13:04
-	340	(behavior response action) and(touch pressure) and emotion and (pet toy robot "novelty item")	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/01/20 13:04
-	118	(behavior response action) and(touch pressure) near4 (sensor dector)) and emotion and (pet toy robot "novelty item")	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/01/20 13:24

-	2	6415439.pn.	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/01/20 13:25
-	1	2002/0049833	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/01/20 13:27
-	0	"2002/0049833".PN.	USPAT	2004/01/20 13:25
-	0	"2002/0049833".PN.	USPAT	2004/01/20 13:26
-	15	("5729598" "5737414" "5745556" "5745884" "5771273" "5794221" "5802283" "5884262" "5889845" "5995138" "6028917" "6031975" "6243450" "6292478" "6314169" "2002/0049833").PN.	USPAT	2004/01/20 13:26
-	0	kikinis and 719/219.ccls.	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/01/20 13:27
-	303	kikinis near3 dan	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/01/20 13:49
-	2	toshihiro and (pet near3 robot)	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/01/20 13:49
-	42	(action response behavior) and (touch pressure) and emotion and (toy robot) and (704/275.ccls. 704/272.ccls. 704/231.ccls. 700/248.ccls. 700/243.ccls. 318/568.12.ccls. 704/209.ccls. 704/207.ccls. 704/270.ccls.)	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/01/20 14:51
-	174	(action response behavior) and (touch pressure) and (detect\$5 emotion) and (toy robot) and (704/275.ccls. 704/272.ccls. 704/231.ccls. 700/248.ccls. 700/243.ccls. 318/568.12.ccls. 704/209.ccls. 704/207.ccls. 704/270.ccls.)	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/01/20 14:52
-	18	(action response behavior) and (touch pressure) and (detect\$5 near5 emotion) and (toy robot) and (704/275.ccls. 704/272.ccls. 704/231.ccls. 700/248.ccls. 700/243.ccls. 318/568.12.ccls. 704/209.ccls. 704/207.ccls. 704/270.ccls.)	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/01/20 15:09
-	19	(action response behavior) and (detect\$5 near5 emotion) and (pet toy robot) and (704/275.ccls. 704/272.ccls. 704/231.ccls. 700/248.ccls. 700/243.ccls. 318/568.12.ccls. 704/209.ccls. 704/207.ccls. 704/270.ccls.)	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/01/20 15:17
-	59	(action response behavior) and (detect\$5 near5 emotion) and (pet toy robot)	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/01/20 15:34
-	5	(action response behavior) and (detect\$5 near5 emotion) and (electronic near3 pet)	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/01/20 15:35
-	163	sony and (pet near3 robot)	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/01/20 15:35
-	14	(robot toy) and (transition near3 probability) and dictionary	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/01/22 10:48

-	104	(robot toy) and (transition near3 probability)	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/01/22 10:57
-	2	(robot toy) and (probability near3 automaton) and (dictionary)	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/01/22 10:58
-	4	(probability near3 automaton) and (dictionary)	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/01/22 11:02
-	43	(toy robot) and (HMM) and (dictionary)	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/01/22 11:02
-	3196	robot and (transition probability)	USPAT	2004/01/22 15:49
-	30	robot and (transition near3 probability)	USPAT	2004/01/22 15:49
-	16	robot and (transition near3 probability) and automaton	USPAT	2004/01/22 15:53
-	4	toy and (transition near3 probability) and automaton	USPAT	2004/01/22 15:53
-	39	(transition near3 probability) and automaton	USPAT	2004/01/22 15:54
-	415	(algorithm near4 sequence) and robot	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/01/22 15:55
-	1	(algorithm near4 sequence near4 action) and robot	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/01/22 15:55
-	1	(algorithm near4 sequence with action) and robot	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/01/22 15:56
-	6	(algorithm near4 sequence) and robot and automaton	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/01/22 15:57
-	44	(algorithm near4 sequence) and toy	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/01/22 16:14
-	0	(automation near4 probablility) and transition	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/01/22 16:14
-	0	automation near4 probablility	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/01/22 16:14
-	0	sequence near4 probablility	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/01/22 16:15
-	1249	(sequence with (action response)) and robot	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/01/22 16:16
-	86	(sequence with (action response)) and robot and dictionary	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/01/22 16:20
-	619	(sequence with (action response)) and toy	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/01/22 16:21

-	45	(sequence with (action response)) and toy and dictionary	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/01/22 16:21
-	0	(probability with sequence with (action response)) and toy and dictionary	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/01/22 16:21
-	1	(probability same sequence with (action response)) and toy and dictionary	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/01/22 16:22
-	11	(probability same sequence with (action response)) and (toy robot)	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/01/22 16:24
-	2	(probability same sequence with (behavior)) and (toy robot)	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/01/22 16:25
-	166992	autonomous adaptation	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/01/22 16:26
-	12	autonomous near3 adaptation	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/01/22 16:37
-	9	shibata and (pet near3 robot)	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/01/22 16:37